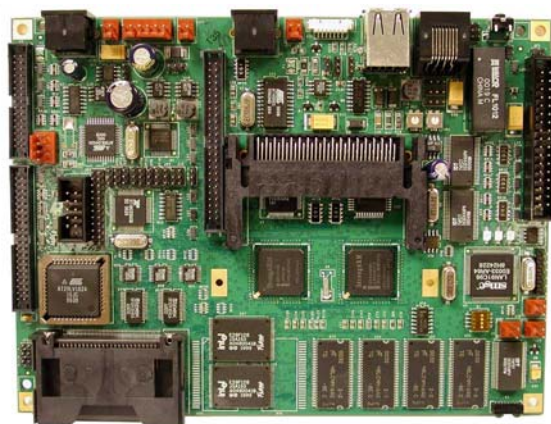




*Embedded Computer Systems*

# Graphics Master User's Manual

ADS document # 110110-9001B



Applied Data Systems

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## Revision History

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REV	DESCRIPTION	DATE	BY
A	Initial release	4/25/01	ak
B	Clarify USB settings, descriptions and usage (sections 3.6.13 and 3.6.14) Add information about ADSmartIO power (section 3.6.15) Add note about IrDA control (3.7.7) Clarify and add details about backlight control signals (section 3.7.13) Add power consumption measurements (4.5) Expand and clarify Power Management description (section 4.6) Correct A/D input voltage range, ADSmartIO (section 4.8.1) Edit for improved readability	10/08/01	ak

## About the Cover Photo

The cover photo shows a fully populated Rev A Graphics Master with 16MB of onboard flash.

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# 1 Introduction

## 1.1 Overview

The Graphics Master is a full-featured single board computer using the SA-1110 StrongARM RISC microprocessor. The Graphics Master is designed to meet the needs of embedded and graphical systems developers.

## 1.2 What's New for the Graphics Master?

If you're familiar with the successful design of the Graphics Client Plus, you find that Graphics Master shares many of the same core features. However, the Graphics Master adds significant new functionality.

### 1.2.1 New Features

- ✓ Compact flash socket
- ✓ Onboard temperature sensing circuit
- ✓ Support for advanced power management
- ✓ StrongARM SA-1111 companion chip:
  - USB master
  - Support for external AC'97 codec
  - PS/2 mouse
- ✓ Quad UART:
  - Ports A and B: Factory configured for 9-wire RS-232 or 3.3V CMOS
  - Ports B and C: 5-wire 3.3V CMOS
- ✓ Supports J1708
- ✓ Enhanced power management ("pulled plug protection")

### 1.2.2 Changes in Connectors

The following signals have changed on Graphics Master connectors. See the related connector descriptions for details.

- GPIOs 24 and 27 are no longer available on connector J7 (3.7.7)
- The location of GPIO 25 on connector J7 has changed (3.7.7)
- SA-1111 SSP signals are made available on pins 36 and 38 of J7 (3.7.7)
- New connector J20 with quad UART, AC'97 codec signals and additional ADSmartIO™ ports.

### 1.2.3 Form Factor

The Graphics Master is slightly larger than the Graphics Client Plus. Placement of the connectors has also changed to better accommodate panel-mounting of the board. Consult the mechanical drawings in section 4.2 for details.

## 1.2.4 Other Key Differences

If you have developed an application on the Graphics Client Plus, here are additional important differences you should know about the Graphics Master. Related sections in this manual are referenced in parentheses.

- Onboard LEDs 1 and 2 are now controlled by GPIO25 and 26, respectively. They can also be controlled by off-board signals. (3.5)
- The SA-1111 has assumed a number of the functions formerly controlled by other systems on the Graphics Client Plus. These include:
  - PCMCIA and Compact Flash
  - Software control of Vee (3.6.8)
  - System controller
  - Backlight intensity (J13 pin 6)
- ADSmartIO can continue to run when system is asleep<sup>1</sup> (JP24, 3.6.15)
- The backlight on/off signal (J13 pin 5) is driven by the system controller

## 1.3 Features

### 1.3.1 Processor

- SA-1110 32-bit StrongARM
- SA-1111 Companion Chip
- Clock rates up to 206 MHz

### 1.3.2 Memory

- 16, 32 or 64 MB synchronous DRAM (1/2 of CPU clock)
- 8, 16 or 32 MB Flash
- 3.3 and 5V PCMCIA

### 1.3.3 Communications

- Ethernet, RJ45
- CAN bus
- USB Master with four-port hub; USB Client port
- Seven Serial Ports
  - Serial 1: RS-232, RS-422, RS-485 or J1708
  - Serial 2: RS-232, 3.3V CMOS or IrDA
  - Serial 3: RS-232
  - Serial A and B: RS-232 or 3.3V CMOS
  - Serial C and D: 3.3V CMOS

---

<sup>1</sup> With optional firmware. Contact technical support if needed.

### 1.3.4 User Interface and Display

- Flat panel interface
- Onboard Vee generator
- Analog touch panel interface
- PS/2 keyboard and mouse interfaces

### 1.3.5 I/O

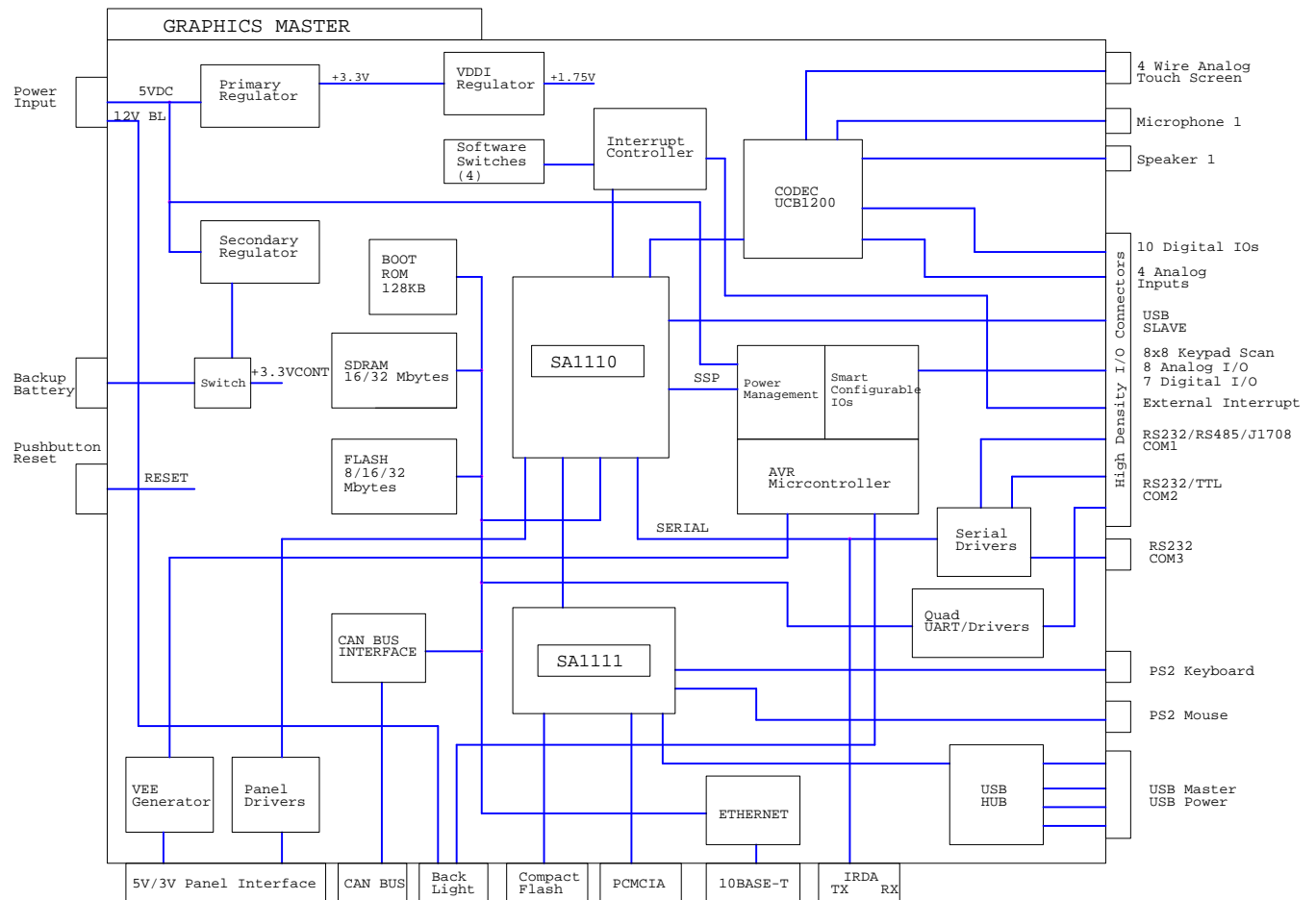
- ADSmartIO™ configurable for digital I/O, A/D inputs and keypad scanning
- Four 10-bit analog inputs
- Contact closure detection
- Digital I/Os from processor

### 1.3.6 Audio

- Speaker output
- Microphone input
- Support for external AC97 codec

## 1.4 Block Diagram

The following diagram illustrates the system organization of the Graphics Master.



## 2 Getting Started

### 2.1 Evaluation Systems

Graphics Master boards are shipped as evaluation systems designed to get the developer up and running quickly.

*To use the system, simply plug power supply into the mini DIN-8 receptacle on the system.*

If the screen does not display anything after five to ten seconds, check the *Frequently Asked Questions*, below. Most operating systems cold boot within twenty seconds.

An evaluation system consists of the following:

- Graphics Master single-board computer
- Flat panel display and cable
- Backlight inverter
- Touch screen and cable
- 120VAC power supply
- Plexiglas mounting
- Developer's Cable Kit including
  - Serial Port 3 DB9 adapter (ADS cable #610110-4004A)
  - Serial Port 1 and 2 DB9 adapter (ADS cable #610110-4007A)
  - DB9F/F null modem cable
- Operating system of your choice
- User's Guide (this document and operating system guide)
- Information about how to access ADS technical resources for the operating system you have chosen.

Make sure you have received *all* the components before you begin your development.

### 2.2 Frequently Asked Questions

The following are some of the most commonly asked questions for evaluation systems:

**Q: When I turn on power, my screen is white and nothing comes up on it.**

A: Check the connector seating. The flat panel connector may have come loose in shipping. Press it firmly into the panel and reapply power to your system.

**Q: What does the pushbutton do?**

A: The push button (SW1) issues a hard reset to the processor, which restarts the real-time clock and may clear memory (RAM). Your application will most likely leave the system in sleep mode when not in use, so this button will rarely be used by your customers. (ref. section 3.2.1)

**Q: Do I have to turn off the system before I insert a PCMCIA or compact flash card?**

A: Generally, no. The Graphics Master supports hot-swapping of PCMCIA and compact flash cards. Consult the operating system documentation for details.

**Q: Do I need to observe any ESD precautions when working with the system?**

A: Yes. If possible, work on a grounded anti-static mat. At a minimum, touch an electrically grounded object before handling the board or touching any components on the board.

**Q: What do I need to start developing my application for the system?**

A: You will need a flash ATA card (8MB or larger) and the cables supplied with your system to interface your development station to the system. For further direction, consult the ADS guide for the installed operating system.

**Q: Who can I call if I need help developing my application?**

A: ADS provides technical support to get your development system running. For customers who establish a business relationship with ADS, we provide support to develop applications and drivers.

**Q: Is there online support?**

A: Yes. Information about the Graphics Master hardware (such as this manual) is available on the ADS product page. ADS has operating-system-specific sites to support its customers. You should have received information about ADS's developers' web site for the operating system you have selected.

**Q: Can I upgrade the version of the operating system?**

A: Yes. ADS provides regular operating system updates on its developers' web site. For operating systems not maintained by ADS, contact the operating system vendor.

**Q: I would like to interface to a different display panel. How can I do this?**

A: ADS may have already interfaced to the panel you are interested in. Consult ADS for availability. ADS can interface to just about any panel you provide.

**2.3 Organization of this Manual**

The manual organizes information in three key sections:

<b>Introduction</b>	Provides an overview of the functionality and organization of the Graphics Master.
<b>Hardware Reference</b>	Describes the configuration settings and connector pinouts for all systems of the Graphics Master.
<b>System Integration</b>	Provides key information about power management, tips for system integration and electrical and mechanical interface specifications.

To locate the information you need, try the following:

1. Browse the *Table of Contents*. Section titles include connector designators and their function.
2. Follow cross-references between sections.
3. View and search this manual in PDF format

**2.4 For Further Information...**

ADS maintains a web site exclusively for its developers. The site includes downloads, troubleshooting guides, operating system updates and the "ADS Knowledge Base", a comprehensive document with dozens of questions answered about developing applications for ADS products. Instructions on how to access the site are shipped with every evaluation system.

## 3 Hardware Reference

This section gives an overview of the hardware features of the Graphics Master. This overview includes a description of the switches, jumper settings, connector and connector pinouts.

### 3.1 Locating "Pin 1"

Many connectors and headers have a visible number on the board that indicates pin 1. If that pin is not clearly marked, there are two other ways to locate pin 1:

1. The easiest method is to look at the underside of the board. The square pad is pin 1.
2. You can determine pin 1 from the mechanical drawing provided in section 4.2.

### 3.2 Switches

#### 3.2.1 SW1: Reset Switch

SW1 is the reset switch for the Graphics Master. This switch issues a hardware reset to the SA-1110. Press this button to restart the Graphics Master without cycling power. This operation will reset the real-time clock. Most operating systems clear the contents of DRAM upon hardware reset.

You can hold the Graphics Master in reset by pressing and holding this button.

#### 3.2.2 S1: DIP Switch

S1 is a four-position DIP switch. It connects to the system/interrupt controller. The settings of individual switches can be read from the controller. Some operating systems on the Graphics Master reserve these switches for their use. Consult the operating system manual for details.

### 3.3 Potentiometers

#### 3.3.1 VR1: Contrast Adjustment

You can adjust Vee (panel contrast) with the single-turn potentiometer VR1 on boards that have the Vee option installed. You may also control Vee through software with the ADSmartIO controller. See J19, JP12 and your operating system reference for further details.

#### 3.3.2 VR2: Passive Panel Voltage Adjustment

You can adjust the VCON voltage on J14 pin 33 with the single-turn potentiometer VR2 on boards that have that option installed. This potentiometer may be replaced by fixed resistors or not installed at all in some Graphics Master configurations.

### 3.4 ADSmartIO™

ADSmartIO™ is a second RISC microcontroller on the Graphics Master. This device provides additional I/O functionality for specialized tasks. Your application software can configure the standard ADSmartIO firmware for a variety of functions, including digital I/O, A/D and keypad scanning.

ADSmartIO ports are available on J2 and J7. Consult your operating system reference guide for the Graphics Master for details on how to make use of the ADSmartIO functionality.

### 3.5 Onboard LEDs

The Graphics Master has three onboard LEDs. They are mapped as follows:

Signal	GPIO line	Part Designator	Color
<i>LEDOUT0</i>	<i>20</i>	<i>D3</i>	<i>Green</i>
<i>LEDOUT1</i>	<i>25</i>	<i>D2</i>	<i>Amber</i>
<i>LEDOUT2</i>	<i>26</i>	<i>D1</i>	<i>Red</i>

Note that, because GPIO25 and 26 also run to connector J2, LEDs 1 and 2 can be driven by or used to monitor an external 3.3V signal. If you do this, make sure to configure the SA-1110 port(s) as input to avoid contention.

### 3.6 Jumper Settings

Jumpers on the Graphics Master select a variety of operational options. All use 2mm shorting blocks (shunts) to select settings. Make sure power is turned off to the Graphics Master when changing the position of a shunt.

#### 3.6.1 JP1: Flat Panel Voltage Select

This jumper selects the supply voltage for the flat panel. The voltage selected here is passed to the *PNL\_PWR* connection (pins 28 and 29) on J12.

Jumper setting	Voltage Selected
<i>1-2</i>	<i>3.3 V</i>
<i>2-3</i>	<i>5.0 V</i>

**WARNING!** Make sure you have selected the correct voltage before connecting the panel. Flat panels are sensitive to--and are often irreparably damaged by--incorrect voltages.

#### 3.6.2 JP2: Panel RL

Type: 2-post header, 2mm

On some active flat panel displays, this signal flips the displayed image right-to-left.

Jumper settings	Connect RL to...
<i>1-2</i>	<i>Ground</i>
<i>none</i>	<i>PNL_PWR</i>

#### 3.6.3 JP3: Panel UD

Type: 2-post header, 2mm

On some active flat panel displays, this signal flips the displayed image bottom-to-top.

Jumper setting	Connect UD to...
<i>1-2</i>	<i>Ground</i>
<i>none</i>	<i>PNL_PWR</i>



### 3.6.4 JP5: Source of Sleep Mode Power

Type: 3-post header, 2mm

This jumper selects the source of power to back up the Graphics Master when it is in sleep mode. See J5 for further details.

Jumper setting	Power supplied by
1-2	VPERM
2-3	VCC (+5V_IN)

### 3.6.5 JP6: Onboard 3.3V Converter Select

Type: 3-post header, 2mm

This jumper selects between an external 3.3V supply (+3.3V\_IN) and the onboard 3.3V supply (+3.3VINT), if installed. The onboard supply is installed as an option on the Graphics Master. J5 is the source of the external 3.3V supply.

Jumper setting	+3.3V connected to
1-2	+3.3V_IN (external)
2-3	+3.3VINT (internal)

### 3.6.6 JP7: Serial Port 2 Mode Select

Type: 2x12 header, 2mm

This header selects the communications mode of Serial Port 2 of the SA-1110. Odd-numbered pins are on the side closer to the outer edge of the Graphics Master. Pins 1 and 2 are closest to U7.

The operating system must configure the processor for the target serial mode. The table below lists the standard voltages to expect on the transmit line of the port when the transmitter is idle.

Important: When using Serial 2 as IrDA, make sure that the operating system configures the port as IrDA. Otherwise, the transmitter may be turned on continuously, which will drain significant amounts of power and may damage IrDA transmitter.

Serial 2 Mode	JP7 Shunt Settings	Tx V <sub>idle</sub>
RS-232	1-2, 3-4, 5-6, 7-8, 9-10, 15-16, 17-18, 23-24	-6 V
3.3V CMOS	1-3, 5-7 13-14, 21-22	3.3 V
IrDA	11-12, 19-20	0 V

### 3.6.7 JP8 to JP11, JP14/15, JP25/26: Serial Port 1 Mode Select

Type: 3-post headers, 2mm

Jumpers JP8 through JP11 select between RS-232 and RS-485/422 mode and set the duplex mode of RS-485/422/J1708.

RS-422, RS-485 and J1708 are differential serial protocols with the same voltage characteristics. RS-422 is a point-to-point protocol while RS-485 and J1708 turn off the transmitter when not in use, allowing multi-drop installations. J1708 enables the transmitter only when transmitting a "1" while RS-485 powers the transmitter for high and low output. RS-485 and RS-422 can be

configured in half- or full-duplex mode. The Graphics Master supports RS-422 by leaving the transmitter enabled all the time.

In half-duplex mode, TX+/RX+ and TX-/RX- are shorted together. Half-duplex devices can see their own transmissions. Connect to either of either the + or – connection on J7, but make sure to observe correct polarity.

For diagnostic purposes, RS-485/422 signals are available on jumper pins as follows: JP8.1 TX+, JP8.2 RX+, JP11.1 TX-, JP11.2 RX-.

The following table indicates shunt settings for each mode of Serial Port 1 (jumpers 24-26 are included, but shown unconnected; settings for those shunts are described in sections 3.6.15 to 3.6.17).

Important: RS-485/422 is installed on standard evaluation systems. J1708 must be factory-configured

	JP25	JP14	JP24	JP26	JP11	JP8	JP10	JP9	J15	JP15
RS-232	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3 4 5 6	1 2 3
RS-485/422 Half Duplex (two-wire)	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3 4 5 6	1 2 3
RS-485/422 Full Duplex (four-wire)	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3 4 5 6	1 2 3
J1708	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3 4 5 6	1 2 3

### 3.6.8 JP12: Flat Panel Vee (Contrast) Adjust Mode

Type: 3-post header, 2mm

Selects if panel Vee will be adjusted electronically or manually. Vee determines the contrast for some panels. The polarity of Vee is set by J19.

Jumper setting	Voltage Selected
1-2	Vee adjusted by PWM from SA-1111 PWM1
2-3	Adjust voltage with potentiometer VR1

### 3.6.9 JP13: Flat Panel Data Voltage Select

Type: 3-post header, 2mm

This jumper selects the voltage of the data lines for the flat panel display.

Important: These jumpers are set at the factory to match the panel and drivers shipped with the system. They should not be changed by the user. You may damage the panel or panel drivers if you change this jumper setting.

Tip: Most 5V panels will run correctly with 3.3V data.

Jumper setting	Voltage Selected
1-2	3.3 V
2-3	5.0 V

### 3.6.10 JP16: DCD-DTR loopback

Type: 2-post header, 2mm

This jumper loops the DTR signal of Serial Port 3 back out to DCD, which can simplify external cabling for null modem connections. This jumper, along with JP17, can create a null modem connection for some serial connections.

Jumper setting	Function
1-2	shorts pins 1(DCD) and 7(DTR) of J10

### 3.6.11 JP17: DSR-DTR loopback

Type: 2-post header, 2mm

This jumper loops the DTR signal of Serial Port 3 back out to DSR. See notes for JP16.

Jumper setting	Function
1-2	shorts pins 2(DSR) and 7(DTR) of J10

### 3.6.12 J19: Flat Panel Vee Select

Type: 6-post header, 2mm

This jumper selects both the source and polarity of the Vee voltage for the flat panel.

The control of Vee is set by JP12. You can adjust Vee either with VR1 (section 3.3) or through software (JP12, section 3.6.8).

Note that Vee is installed only as an option and is not installed on all Graphics Master boards.

Jumper setting	Voltage Selected
none	none
2-4	Positive Vee
4-6	Negative Vee
3-4	+12V from J5.4
others	none

**WARNING!** Make sure you have selected the correct voltage before connecting the panel. Flat panels are sensitive to--and are often irreparably damaged by--incorrect voltages.

### 3.6.13 JP20/21: USB Hub Bypass/Tier Level Select

Type: 3-post headers, 2mm

These shunts select whether the SA-1111 or an external, upstream hub control the onboard USB hub. The Graphics Master can act as the root (highest-level, Tier 0) node in the USB network or can connect below another USB hub (in this case, the SA-1111 is disconnected from the USB network). Setting the shunts to position 2-3 directly connects the SA-1111 master signal to USB Hub 4 lines for systems that do not have the USB hub installed.

Important: Both shunts must be set to the same position.

Jumper setting	System acts as USB...
1-2	...Tier 0 (root node) connection
n/c	...Tier 1 connection
2-3	...single-port master on Hub 4

### 3.6.14 JP22/23: USB Internal Loopback

Type: 3-post headers, 2mm

These shunts connect the SA-1110 USB Slave port to Hub Downstream Port 1, creating an onboard USB loopback. If this loopback is used, do not use the connections on J20 or J23. The SA-1110 USB Slave port is always available on header J2.

Important: Both shunts must be set to the same position.

Jumper setting	USB Hub Port 1...
n/c	...is only connected to J20 & J23
1-2	...also loops back to SA-1110 USB Slave

### 3.6.15 JP24: ADSmartIO™ Power Source

Type: 3-post header, 2mm

This jumper selects the power supply for the ADSmartIO. You may turn off ADSmartIO to conserve power in sleep mode, or leave it on to continue performing base I/O functions or to assist with power management. Note that your system may require special firmware to support this feature.

Important: If ADSmartIO is turned off when in sleep mode, all its outputs will be off.

Jumper setting	In Sleep mode, ADSmartIO is...
1-2	OFF
2-3	ON

### 3.6.16 JP25: Serial 1 Rx Receiver

Type: 3-post header, 2mm

This jumper selects what device on the Graphics Master will receive data from the Serial 1 receive input (J7 pin 12).

Jumper setting	Serial 1 Rx Source
1-2	StrongARM CPU
2-3	ADSmartIO

### 3.6.17 JP26: Serial 1 Tx Source

Type: 3-post header, 2mm

This jumper selects what device on the Graphics Master supplies data to the Serial 1 transmit output (J7 pin 14).

Jumper setting	Serial 1 Tx Source
1-2	StrongARM CPU
2-3	ADSmartIO

## 3.7 Connector Pinouts

The following tables describe connector pinouts and the type of connector. At least one pin of every connector is labeled on the Graphics Master. Double-row headers on the board are all numbered as shown in the figure to the right.

2	4	6	8...
1	3	5	7...

For information about the location of the connectors on the Graphics Master, refer to section 4.2, *Mechanical Specifications*:

Legend:            n/c     Not connected  
                      GND     Graphics Master ground plane

### 3.7.1 J1: Contact Closure Detect

Type: 2-pin header, 0.100-in spacing, friction lock, Molex 22-23-2021

Recommended mating connector: Molex 22-01-3027

External input. Short these pins together to generate a high level on GPIO1 of the SA-1110. Pin 2 can be used by the application or operating system for user input, contact closure detection or to wake the system from sleep mode.

Pin	Signal name	Description
1	GND	Ground
2	SWITCH	to GPIO1 of SA-1110 via inverting buffer; includes 11kΩ pull-up to 3.3V and is powered. during Sleep

### 3.7.2 J2: USB, A/D, Digital I/O

Type: 2x15 header, 2 mm spacing, Samtec STMM-115-02-T-D

Recommended mating connector: TCSD-15 series from SAMTEC

Electrical specifications for signals are referenced in parentheses ( ).

Pin	Signal name	Pin	Description	
1	UCB IO0		Digital I/Os (10) (UCB1200, section 4.8.2)	
3	UCB IO1			
5	UCB IO2			
7	UCB IO3			
9	UCB IO4			
	UCB IO9			2
	UCB IO8			4
	UCB IO7			6
	UCB IO6			8
	UCB IO5			10

Pin	Signal name	Pin	Description	
11	ANIN0		Analog inputs (4) (UCB1200, section 4.8.2)	
13	ANIN1			
15	ANIN2			
17	ANIN3			
	SMTIO0	12	PB0	ADSmartIO lines (7)  (section 4.8.1)
	SMTIO1	14	PB1	
	SMTIO2	16	PB2	
	SMTIO3	18	PB3	
	SMTIO4	20	PD0	
	SMTIO5	22	PD1	
	/EXT_IRQ	24	External interrupt 3.3V CMOS with 10k pullup	
19	UCB TINP		Telecom interface (UCB1200, section 4.8.2)	
21	UCB TINN			
23	UCB TOUTN			
25	UCB TOUTP			
	USB VCC	26	USB Slave (SA-1100)	
27	USB GND			
	USB UDC-	28		
	USB UDC+	30		
29	GND		Ground	

### 3.7.3 J3: Battery Connector

Type: 2-pin header, 0.100-in spacing, friction lock, Molex 22-23-2021

Recommended mating connector: Molex 22-01-3027

This connector allows you to connect an external battery to back up power on the Graphics Master. If no other power source is available, the system will draw its sleep mode current (section 4.5) from this connection. There is a steady-state 1M $\Omega$  load across these terminals. For reliable operation of the Graphics Master, place a 0.100" shunt across the pins of this connector.

Pin	Signal name	Description
1	BATPOS	3 Volt battery, positive terminal
2	BATNEG	Graphics Master ground

### 3.7.4 J4: Touch Panel

Type: 4-pin header, 0.100-in spacing, friction lock, Molex 22-23-2041

Recommended mating connector: Molex 22-01-3047

The mapping shown of signal to edge of touch panel is an ADS convention. Interface cables are constructed to match this order. Some operating systems can tolerate swapping of positive (P) and negative (M) connections, and even swapping of X and Y pairs.

Pin	Signal name	Description
1	TSMX	Left edge of panel
2	TSPX	Right
3	TSPY	Bottom
4	TPMY	Top

### 3.7.5 J5: Power Input

Type: 6pin header, 0.100-in spacing, friction lock, Molex 22-23-2061

Recommended mating connector: Molex 22-01-3067

This connector supplies main and backup power to the Graphics Master. See section 4.3 for additional details about input power requirements.

Pin	Signal name	Description
1	+5V_IN	main power: +5 Volts $\pm 5\%$
2	GND_IN	Ground (filtered)
3	+3.3V_IN	+3.3 Volts $\pm 5\%$ Required if onboard 3.3V supply option is not installed To use, set JP6 to "external 3.3V."
4	+12V_IN	Optional 12V for PCMCIA (J11), backlight (J13) and Vee (J19)
5	Power_Enable	3.3V CMOS output; 0V when board power is disabled see section 4.3.7 for further details
6	VPerm	5-12V DC @5mA for sleep mode

### 3.7.6 J6: PS/2 Trackpad/Keyboard Input

Type: Mini DIN-6 socket housing, MDI-004-6PC

Recommended mating connector: PS/2 keyboard

Pin	Signal name	Description
1	TPSIG	PS/2 trackpad/keyboard data
2	N/C	not connected
3	GND	Ground
4	VCC	+ 5 Volts, fused at 350 mA
5	TPCLK	PS/2 trackpad/keyboard clock
6	N/C	not connected

### 3.7.7 J7: Serial Ports 1 and 2, Matrix Keypad, Power Outputs

Type: 2x20 header, 2 mm spacing

Recommended mating connector: TCSD-20 series from SAMTEC

Pin	Signal name	Pin	Description
1	ROW0	PC7	ADSmartIO (see section 4.8.1)  Configurable as: Digital I/O Keypad, rows
3	ROW1	PC6	
5	ROW2	PC5	
7	ROW3	PC4	
9	ROW4	PC3	
11	ROW5	PC2	
13	ROW6	PC1	
15	ROW7	PC0	
	RXD2	2	SA-1110 Serial Port 2  RS-232 or CMOS (see JP7) See also note below
	TXD2	4	
	CTS2	6	
	RTS2	8	
	GNDCOM2	10	

Pin	Signal name	Pin	Description	
	<i>RXD1</i>	<i>12</i>	<i>RS-232 Serial Port 1 from SA-1110 or ADSmartIO (see section 3.6.7 for mode select, JP25,26 for source select, and note below about handshaking)</i>	
	<i>TXD1</i>	<i>14</i>		
	<i>CTS1</i>	<i>16</i>		
	<i>RTS1</i>	<i>18</i>		
	<i>GNDCOM1</i>	<i>20</i>		
<i>17</i>	<i>COL0</i>		<i>PA0</i>	<i>ADSmartIO (see section 4.8.1)  Configurable as: Analog Inputs Digital I/O Keypad, columns</i>
<i>19</i>	<i>COL1</i>		<i>PA1</i>	
<i>21</i>	<i>COL2</i>		<i>PA2</i>	
<i>23</i>	<i>COL3</i>		<i>PA3</i>	
<i>25</i>	<i>COL4</i>		<i>PA4</i>	
<i>27</i>	<i>COL5</i>		<i>PA5</i>	
<i>29</i>	<i>COL6</i>		<i>PA6</i>	
<i>31</i>	<i>COL7</i>		<i>PA7</i>	
	<i>RX422+</i>	<i>22</i>	<i>RS-422/485 lines, Serial Port 1 (see section 3.6.7)</i>	
	<i>RX422-</i>	<i>24</i>		
	<i>TX422+</i>	<i>26</i>		
	<i>TX422-</i>	<i>28</i>		
	<i>GNDRS422</i>	<i>30</i>		
	<i>GPIO25/LED1</i>	<i>32</i>	<i>SA-1110 GPIOs (see sections 3.5 and 4.8.3)</i>	
	<i>GPIO26/LED2</i>	<i>34</i>		
<i>33</i>	<i>VREF</i>		<i>Voltage reference for ADSmartIO A/D; reference use only (&lt;100µA)</i>	
<i>35</i>	<i>VCC</i>		<i>+5V</i>	
<i>37</i>	<i>+3.3V</i>		<i>+3.3V</i>	
<i>39</i>	<i>GND</i>		<i>Ground</i>	
	<i>C7</i>	<i>36</i>	<i>SA-1111 GPIOs  Ground</i>	
	<i>C6</i>	<i>38</i>		
	<i>GND</i>	<i>40</i>		

Note: The SA-1110 does not have hardware handshaking on its serial lines. The Graphics Master is wired to use SA-1110 GPIO lines to perform CTS/RTS handshaking as follows:

SA-1110 GPIO	Function	
	RS-232	RS-485
<i>14</i>	<i>CTS1</i>	<i>RX enable</i>
<i>15</i>	<i>RTS1</i>	<i>TX enable</i>
<i>16</i>	<i>CTS2</i>	
<i>17</i>	<i>RTS2</i>	
<i>18</i>	<i>CTS3</i>	
<i>19</i>	<i>RTS3</i>	

The IrDA transmitter is enabled with an active-low signal on GPIO23. The enable line has a pull-up to disable the IrDA transmitter during initialization or when GPIO23 is an input.



### 3.7.8 J8: Ethernet

Type: RJ-45 socket, Amp 555167-1

Recommended mating connector: RJ-45 plug.

Connects to the on-board Ethernet driver.

Pin	Signal name	Description
1	ETHP1	Transmit +
2	ETHP2	Transmit -
3	ETHP3	Receive +
4	n/c	
5		
6	ETHP6	Receive -
7	n/c	
8		

### 3.7.9 J9: Manufacturing Test

Type: 6-pin header, 1x6 0.100-inch spacing.

For manufacturing use.

### 3.7.10 J10: Serial Port 3

Type: 2x5 header, 0.100" IDC, keyed

Recommended mating connector: 2x5 IDC

Pin	Signal name	Description
1	"DCD3"	DCD from external device see JP16 for loopback options
2	"DSR3"	DSR from external device see JP17 for loopback options
3	RXD3	SA-1110 Serial Port 3, RS-232
4	RTS3	
5	TXD3	
6	CTS3	
7	"DTR3"	DTR from external device see JP16 and JP17 for loopback options
8	n/c	not connected
9	GNDFIL3	filtered connection to ground
10	n/c	not connected

Note: The SA-1110 does not have hardware handshaking on its serial lines. The Graphics Master is wired to use SA-1110 GPIO lines to perform CTS/RTS handshaking. See the table on page 22 for port assignments.

### 3.7.11 J11: PCMCIA

Production option: Mating ejector Amp #146019-1

The 68-pin PCMCIA socket conforms to the PCMCIA standard for 3.3V and 5V Type II cards. It will supply up to 500 mA of 5V current. The socket is normally de-energized; the operating system is responsible for turning on the socket when a card is inserted and turning it off when the card is removed.

Ejector hardware is available for applications that require regular insertion and removal of PCMCIA cards.

Note:  $V_{PP}$  (pins 18 and 52) is supplied from the "+12V" input (pin 4 on J5). Since few PCMCIA cards manufactured use this voltage, most applications can set the J5.4 input voltage to match the backlight voltage needed. See section 4.3.4 for further details.

### 3.7.12 J12: Flat Panel (Hirose connector)

Type: Hirose 31-pin connector, 1mm pitch, #DF9B-31P-1V

Recommended mating connector: Hirose DF9B-31S-1V

This connector houses the signals to drive an 18-bit flat panel and will drive a Sharp LQ64D343 panel in StrongARM 16-bit mode directly. It can be found on the back side of the Graphics Master. The only difference between this connector and J14 is that J12 does not include  $V_{EE}$ . Signals shown are for the StrongARM in 16-bit mode.

Electrical specifications for panel signals are listed in section 4.8.4.

Pin	Signal name	Description
1	<i>PNL_GND</i>	<i>Panel ground</i>
2	<i>PNL_PIXCLK</i>	<i>Pixel Clock</i>
3	<i>PNL_HSYNC</i>	<i>Horizontal Sync.</i>
4	<i>PNL_VSYNC</i>	<i>Vertical Sync.</i>
5	<i>PNL_GND</i>	<i>Ground</i>
6	<i>PNL_RED0</i>	<i>Red Bit 0 (same as RED5)</i>
7	<i>PNL_RED1</i>	<i>Red Bit 1</i>
8	<i>PNL_RED2</i>	<i>Red Bit 2</i>
9	<i>PNL_RED3</i>	<i>Red Bit 3</i>
10	<i>PNL_RED4</i>	<i>Red Bit 4</i>
11	<i>PNL_RED5</i>	<i>Red Bit 5</i>
12	<i>PNL_GND</i>	<i>Ground</i>
13	<i>PNL_GREEN0</i>	<i>Green Bit 0</i>
14	<i>PNL_GREEN1</i>	<i>Green Bit 1</i>
15	<i>PNL_GREEN2</i>	<i>Green Bit 2</i>
16	<i>PNL_GREEN3</i>	<i>Green Bit 3</i>
17	<i>PNL_GREEN4</i>	<i>Green Bit 4</i>
18	<i>PNL_GREEN5</i>	<i>Green Bit 5</i>
19	<i>PNL_GND</i>	<i>Ground</i>
20	<i>PNL_BLUE0</i>	<i>Blue Bit 0 (same as BLUE5)</i>
21	<i>PNL_BLUE1</i>	<i>Blue Bit 1</i>
22	<i>PNL_BLUE2</i>	<i>Blue Bit 2</i>
23	<i>PNL_BLUE3</i>	<i>Blue Bit 3</i>
24	<i>PNL_BLUE4</i>	<i>Blue Bit 4</i>
25	<i>PNL_BLUE5</i>	<i>Blue Bit 5</i>
26	<i>PNL_GND</i>	<i>Ground</i>
27	<i>PNL_LBIAS</i>	<i>Enable</i>
28	<i>PNL_PWR</i>	<i>Vcc(5V) or 3.3 V, depending on JP1 position</i>
29		
30	<i>PNL_RL</i>	<i>Horizontal Mode Select (set by JP2)</i>
31	<i>PNL_UD</i>	<i>Vertical Mode Select (set by JP3)</i>

### 3.7.13 J13: Backlight Inverter

Type: 7-pin header, 1.25mm, keyed, Molex #53261-0790

Recommended mating connector: Molex 51021-0700 or  
Quadrangle Products kit #RT51021-0700-18

This connector will supply power to a Xentek LS520 backlight inverter and compatible devices with a one-to-one cable. The onboard Graphics Master PWM driver can electronically control the brightness of the inverter. Note that some of the control signals may not work with other backlight inverters (see production options).

Production options: 5V pull-up for *BACKLIGHTON* signal  
Power-up default for *BACKLIGHTON* is not GND

Pin	Signal name	Description
1	+12V	0-12 volts from J5.4 (see J5 and section 4.3.4)
2		
3	GND	Ground
4		
5	<i>BACKLIGHTON</i>	Open-collector output + pullup to enable backlight (shorted to GND for "off") (system controller)
6	<i>BACKLIGHTPWM</i>	PWM brightness control (SA-1111) (3.3V CMOS, 1.2k $\Omega$ series, 1 $\mu$ F filter)
7	GND	Ground

### 3.7.14 J14: Flat Panel (IDC 34)

Type: 34-pin IDC header, 2x17 0.100-inch spacing, shrouded, keyed

Recommended mating connector: IDC connector AMP #1-746288-8

This connector houses the signals to drive an 18-bit flat panel. Electrical specifications for panel signals are listed in section 4.8.4.

Pin	Signal name	Description
1	<i>PNL VEE</i>	$V_{EE}$ (contrast); see VR1, J19 and JP12
2	<i>PNL GND</i>	Ground
3	<i>PNL PIXCLK</i>	Pixel Clock
4	<i>PNL HSYNC</i>	Horizontal Sync.
5	<i>PNL VSYNC</i>	Vertical Sync.
6	<i>PNL GND</i>	Ground
7	<i>PNL RED0</i>	Red Bit 0 (same as RED5)
8	<i>PNL RED1</i>	Red Bit 1
9	<i>PNL RED2</i>	Red Bit 2
10	<i>PNL RED3</i>	Red Bit 3
11	<i>PNL RED4</i>	Red Bit 4
12	<i>PNL RED5</i>	Red Bit 5
13	<i>PNL GND</i>	Ground
14	<i>PNL GREEN0</i>	Green Bit 0
15	<i>PNL GREEN1</i>	Green Bit 1
16	<i>PNL GREEN2</i>	Green Bit 2
17	<i>PNL GREEN3</i>	Green Bit 3
18	<i>PNL GREEN4</i>	Green Bit 4
19	<i>PNL GREEN5</i>	Green Bit 5
20	<i>PNL GND</i>	Ground

Pin	Signal name	Description
21	<i>PNL_BLUE0</i>	<i>Blue Bit 0 (same as BLUE5)</i>
22	<i>PNL_BLUE1</i>	<i>Blue Bit 1</i>
23	<i>PNL_BLUE2</i>	<i>Blue Bit 2</i>
24	<i>PNL_BLUE3</i>	<i>Blue Bit 3</i>
25	<i>PNL_BLUE4</i>	<i>Blue Bit 4</i>
26	<i>PNL_BLUE5</i>	<i>Blue Bit 5</i>
27	<i>PNL_GND</i>	<i>Ground</i>
28	<i>PNL_LBIAS</i>	<i>Enable</i>
29	<i>PNL_PWR</i>	<i>Vcc(5V) or 3.3 V, depending on JP1 position</i>
30		
31	<i>PNL_RL</i>	<i>Horizontal Mode Select (set by JP2)</i>
32	<i>PNL_UD</i>	<i>Vertical Mode Select (set by JP3)</i>
33	<i>PNL_ENA</i>	<i>Panel enable signal (StrongARM GPIO24)</i>
34	<i>VCON</i>	<i>Adjustable voltage for passive panels; set with VR2 or fixed voltage divider</i>

### 3.7.15 J15: Manufacturing Test

Type: 2x3 header, 0.100-inch spacing

For manufacturing use.

### 3.7.16 J16: Speaker

Type: 2-pin header, 0.100-in spacing, friction lock, Molex 22-23-2021

Recommended mating connector: Molex 22-01-3027

A speaker may be connected across the speaker outputs (bridge-tied load). Minimum speaker impedance is eight ohms. Voltages on the speaker outputs are 0-3.3V. If you connect one side of the speaker to ground, you must use a blocking capacitor; in this case, output power will be reduced to one quarter and power consumption will be cut in half from that of the bridge-tied load. Consult the UCB1200 specifications for further details.

Pin	Signal name	Description
1	<i>SPK -</i>	<i>Speaker connection (-)</i>
2	<i>SPK +</i>	<i>Speaker connection (+)</i>

### 3.7.17 J17: Microphone

Type: 2-pin header, 0.100-in spacing, friction lock, Molex 22-23-2021

Recommended mating connector: Molex 22-01-3027

Input impedance of the microphone connection is 25 k $\Omega$ . Specifications for the UCB1200 call for 1k $\Omega$  or electret microphones. Microphones with other impedance may be used. Microphones connected should use a DC blocking capacitor between the microphone and MIC+ input.

Pin	Signal name	Description
1	<i>MIC GND</i>	<i>Microphone (-)</i>
2	<i>MIC +</i>	<i>Microphone (+)</i>

### 3.7.18 J18: CAN Bus

Type: 2-pin header, 0.100-in spacing, friction lock, Molex 22-23-2021

Recommended mating connector: Molex 22-01-3027

Use this connection to connect to a CAN bus. Note that a CAN bus must be terminated at both ends with 120Ω resistors. The Graphics Master does not include termination resistors onboard.

Pin	Signal name	Description
1	CANHIGH	CAN bus (+)
2	CANLOW	CAN bus (-)

### 3.7.19 J20: USB Master, Serial Ports A-D, Codec

Type: 2x25 header, 2 mm spacing, Samtec STMM-125-02-T-D

Recommended mating connector: TCSD-15 series from SAMTEC

Production options: For cost savings in production, UART ports A and B can be configured to use external +/-12V (also on this connector) or to be 3.3V CMOS. On evaluation systems, UART Ports A and B have RS-232 drivers.

Section references in parentheses ( ) are electrical specifications.

Pin	Signal name	Pin	Description
1	HUB4+		<i>USB Hub Downstream Ports (SA-1111)</i>
3	HUB3+		
5	HUB2+		
7	HUB1+		
	HUB4-	2	
	HUB3-	4	
	HUB2-	6	
	HUB1-	8	
9	HUBIN+		<i>Upstream USB hub connection (SA-1111)</i>
	HUBIN-	10	
11	USB VCC HUB		<i>USB power and ground (filtered) (SA-1111)</i>
	USB GND+	12	
13	DATA OUT		<i>External AC'97 Codec (SA-1111)</i>
15	DATA IN	C2	
17	SYNC OUT	C3	
19	BIT CLK IN	C1	
21	SYS CLK	C0	

Pin	Signal name	Pin	Description
	<i>SMTIO6</i>	<i>14</i>	<i>ADSmartIO lines</i>  <i>(section 4.8.1)</i>
	<i>SMTIO7</i>	<i>16</i>	
	<i>SMTIO8</i>	<i>18</i>	
	<i>SMTIO9</i>	<i>20</i>	
	<i>SMTIO10</i>	<i>22</i>	
<i>23</i>	<i>TXDA</i>		<i>Serial Port A</i>  <i>(RS-232 standard,</i> <i>3.3V or ext. +/-12V optional)</i>
<i>25</i>	<i>TXDA</i>		
<i>27</i>	<i>CTSA</i>		
<i>29</i>	<i>RTSA</i>		
<i>31</i>	<i>DTRA</i>		
<i>33</i>	<i>DCDA</i>		
<i>35</i>	<i>DSRA</i>		
<i>37</i>	<i>RIA</i>		
	<i>RXDB</i>	<i>24</i>	<i>Serial Port B</i>  <i>(RS-232 standard,</i> <i>3.3V or ext. +/-12V optional)</i>
	<i>TXDB</i>	<i>26</i>	
	<i>CTSB</i>	<i>28</i>	
	<i>RTSB</i>	<i>30</i>	
	<i>DTRB</i>	<i>32</i>	
	<i>DCDB</i>	<i>34</i>	
	<i>DSRB</i>	<i>36</i>	
	<i>RIB</i>	<i>38</i>	
<i>39</i>	<i>GND FILT</i>	<i>40</i>	<i>Ground (filtered)</i>
<i>41</i>	<i>RXDC</i>		<i>Serial Port C</i> <i>(3.3V CMOS)</i>
<i>43</i>	<i>TXDC</i>		
<i>45</i>	<i>CTSC</i>		
<i>47</i>	<i>RTSC</i>		
	<i>RXDD</i>	<i>42</i>	<i>Serial Port D</i> <i>(3.3V CMOS)</i>
	<i>TXDD</i>	<i>44</i>	
	<i>CTSD</i>	<i>46</i>	
	<i>RTSD</i>	<i>48</i>	
<i>49</i>	<i>EXT+12V</i>		<i>External +/-12V power input</i> <i>for UARTs A &amp; B (optional)</i>
	<i>EXT-12V</i>	<i>50</i>	

### 3.7.20 J22: PS/2 Mouse

Type: Mini DIN-6 socket housing, MDI-004-6PC

Recommended mating connector: PS/2 mouse, mini DIN-6

Pin	Signal name	Description
<i>1</i>	<i>MSDATA</i>	<i>Mouse data</i>
<i>2</i>	<i>N/C</i>	<i>not connected</i>
<i>3</i>	<i>GND</i>	<i>Ground</i>
<i>4</i>	<i>VCC</i>	<i>+ 5 Volts, fused at 350 mA</i>
<i>5</i>	<i>MSCLK</i>	<i>Mouse clock</i>
<i>6</i>	<i>N/C</i>	<i>not connected</i>

### 3.7.21 J23: USB

Type: Dual Type A USB socket

Recommended mating connector: USB cable, Type A/B

Use these ports to connect to downstream USB devices. USB Port A is on the top, Port B is on the bottom (closest to the board).

Pin	Signal name	Description
A1	USB_VCC_OUT	USB A
A2	HUB1-	
A3	HUB1+	
A4	USB_GND	
B1	USB_VCC_OUT	USB B
B2	HUB4-	
B3	HUB4+	
B4	USB_GND	

### 3.7.22 J24: Compact Flash

The 50-pin compact flash socket conforms to the compact flash standard for 3.3V and 5V Type II cards. It will supply up to 500 mA of 5V current. The socket is normally de-energized; the operating system is responsible for turning on the socket when a card is inserted and turning it off when the card is removed.

The socket includes an integral card ejector.

### 3.7.23 J25: Thermistor Input

Type: 2-pin header, 0.100-in spacing, friction lock, Molex 22-23-2021

Recommended mating connector: Molex 22-01-3027

The ADSmartIO controller can read voltages from onboard thermistor Z68 (33k $\Omega$ ) to sense temperature. You may also connect an off-board thermistor to J25 for temperature sensing (make sure Z68 is not populated). ADSmartIO output SMT10 (PD6) controls power to the thermistor, supplying Vref to the THERM+ pin when the port is high.

Pin	Signal name	Description
1	THERM+	Thermistor supply voltage ( <i>Vref</i> switched)
2	ADC+	A/D input

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## 4 System Integration

### 4.1 Tips for System Integration

#### 4.1.1 Strategies for Backup Power

There are several ways to provide backup power to the Graphics Master. Each has advantages that favor particular applications.

**1. No Battery Backup.** Applications that are entirely non-volatile (no critical data is stored in RAM), or that can recover from unexpected power failures, are good candidates for doing without a backup battery.

**2. 3V Battery on J3.** The backup battery supplies power to the system if the onboard 3.3V supply fails. Operating systems with power management will put the system to sleep if they detect that the system is operating from this supply. For this reason, the voltage on J3 must be consistently less than 3.3V (preferably less than 3.2 V).

**3. Use VPERM Input.** The VPERM power source is more flexible than the backup battery in that it can be any voltage between 5 and 12 volts. Set JP5 to use this voltage for sleep mode power. Sleep mode power to the RAM is supplied through a linear regulator, so lower values of VPERM will provide lower sleep mode power consumption.

**4. Use Main Power as Backup.** If the main power supply will be available continuously, set JP5 to use this voltage for sleep mode power. However, all 5V devices onboard (e.g. flash, PCMCIA, compact flash) will continue to be under power during sleep mode, so power savings will be reduced.

#### 4.1.2 Electrical Tips

Keep the following issues in mind when designing a system using the Graphics Master.

- Make sure that the 5V and 3.3V input voltage is stable, clean and robust (computer grade). Droops and instability in the 5V supply can result in erratic operation of PCMCIA and compact flash cards and the flash memory.
- Route the touch panel cabling away from the backlight inverter and other noisy systems. The touch panel driver algorithms can be adjusted to filter out large amounts of noise; however, the touch panel may then be less responsive.
- The backlight frequency can resonate with some flat panels. If beats appear, change the backlight frequency or panel refresh rate.

### 4.2 Mechanical Specifications

The Graphics Master is 5.0 by 6.75 inches in size. This section describes the component dimensions and mounting of the board. Detailed drawings are available from ADS in PDF format for customers who are going into production.

#### 4.2.1 Mechanical Drawing

The following mechanical drawing of the Graphics Master specifies the dimensions of the Graphics Master, as well as locations of key components on the board. The origin for measurements is the center of the mounting hole on the lower left corner of the board.



For reliable ground connections, use locking washers (star or split) when securing a Graphics Master in an enclosure. Make sure that washers do not extend beyond the limits of the pads provided.

### 4.2.3 Clearances

The Graphics Master has a low profile. It can fit in an enclosure as thin as 0.75-in I.D. Key clearances are as follows:

- Highest component: 0.625 inches
- Minimum clearance under board: 0.2 inches
- Minimum overall height requirement: 0.75 inches

Note: Selection of connectors and wiring harnesses will determine height of final assembly.

## 4.3 Input Power Requirements

Power is supplied to the Graphics Master through connect J5. A backup battery may also be connected to J3. All power inputs have EMI filtering. The following are the power inputs to the Graphics Master.

### 4.3.1 +5.0V

The Graphics Master requires a high-quality DC input of 5.0 VDC ( $\pm 5\%$ ) to operate normally. This voltage is used to generate additional on-board voltages, but also supplies many ICs directly. For this reason, it should be well regulated and filtered. The 5V supply enters the board on pin 1 of J5.

The quality of the 5V supply is very important. Droop or instability in this supply can lead to intermittent failures of board systems including, but not limited to the PCMCIA and compact flash slots and flash disk.

Note: Some configurations that do not have all options populated can tolerate voltages different from 5.0V on this input. Consult ADS if you think this will be necessary or useful for your application.

### 4.3.2 +3.3V

You may want to supply 3.3V power to the Graphics Master in the following cases:

- The 3.3V power supply option is not installed in your build of the Graphics Master
- Additional 3.3V current is needed (e.g. for flat panel) than the Graphics Master can supply

In either case, you must set JP6 to "External 3.3V" to utilize the external power. As with the 5V supply, the 3.3V power must be of the highest quality, as it supplies many ICs directly. An external 3.3V power is supplied to the Graphics Master on pin 3 of J5.

### 4.3.3 VPERM

If JP5 is set to use it, VPERM will supply power to the real-time clock and to DRAM during sleep mode. VPERM can be any voltage between 5 and 12 volts. VPERM enters the Graphics Master on pin 6 of J5.

Note: VPERM is regulated down to 3.3V internally. While VPERM can be as high as 30V, most of the energy will be converted to internal heat gain. Under most conditions, ADS does not recommend VPERM to be higher than 12V.

#### 4.3.4 +12V (J5)

The "+12V" input on J5 supplies power to the backlight connector (J13) and  $V_{PP}$  on the PCMCIA socket (J11). Because modern PCMCIA cards rarely use  $V_{PP}$ , this voltage can usually be set to any voltage between 0 and 12V to match the needs of the backlight inverter. If the backlight is not connected to J13, this voltage can be left unconnected. "+12V" is supplied to the board on pin 4 of J5.

#### 4.3.5 +/-12V (RS-232)

If Serial Ports A and B on your system are configured for +/-12V operation, you must supply +/-12V to pins 49 and 50 of J20 for proper operation of those ports.

#### 4.3.6 3.0V Battery Backup (J3)

Your system may include an external 3.0V battery to back up RAM and the real-time clock during sleep mode. If this voltage exceeds 3.1V it may interfere with power management circuits. See section 4.1.1 *Strategies for Backup Power* for details on power management.

#### 4.3.7 "Power On" Output

Use the "Power On" output from J5 pin 5 to control external power supplies (e.g. 5V and 3.3V) if power conservation is important. This signal is high when the system is running and low when the system is asleep.

Note that the VPERM voltage, if used, should remain on regardless of the state of the Power On signal.

#### 4.3.8 EMI/RFI and Transient Suppression

It is the responsibility of the user to provide surge protection on the input power lines. This is especially important if the power supply wires will be subject to EMI/RFI or ESD (see also section 4.7).

### 4.4 Externally Available Voltages

The Graphics Master generates voltages for the processor and other on-board logic. Some of these power sources are available externally as follows:

Voltage	Maximum Output Current	Connector
VCC (+5V)	500 mA <sup>2</sup>	J7, pin 35
+3.3V	100 mA	J7, pin 37
5V, keyboard	350mA	J6, pin 4
Panel Power (based on JP1 setting)	250 mA	J12, pins 28 and 29 J14, pins 29 and 30
Panel Vee	25 mA	J14, pin 1

<sup>2</sup> Primarily dependent on external 5V power supply, but also limited by connectors and power plane onboard.

## 4.5 Power Consumption

The Graphics Master has been designed to use a minimum of power. When not active, the SA-1110 can be put into Idle or Sleep modes, further reducing power consumption.

The following measurements were made using production systems<sup>3</sup>. Measurements were taken using 5V input power, 5V and 3.3V input power and with the system in sleep mode running only on VPERM.

Mode	Current
5V only	530 mA
5V with external 3.3V	150mA on 5V 430mA on 3.3V
Sleep (VPERM) <sup>4</sup>	< 3 mA

Actual power consumption varies according to LCD panel connected, processor activity and peripheral electrical connections. Temperature and input voltage affect power consumption to a lesser extent

## 4.6 Power Management

The StrongARM processor supports three power management modes: Run, Idle and Sleep. Transitions between Run and Idle are handled automatically by the operating system. The system enters and exits low-power Sleep mode based on user and application commands.

In Sleep mode, the system keeps the RAM in self-refresh and maintains the StrongARM real-time clock. All other systems are disabled but continue to draw 3.3 and 5V power. For full power savings during Sleep, use the Power\_Enable signal to turn off external power (see J5 and section 4.3.7 for details).

### 4.6.1 Using Sleep Mode for Power Management

Each operating system has a command to put the system to sleep through software. Some operating systems support using header J1 as a "power switch" to toggle the system between Run and Sleep states. Your operating system may also include the option to wake the system after a pre-determined amount of time.

### 4.6.2 Sleep Mode and Power Failures

The Graphics Master generates an interrupt when the main power (J5.1) fails. The operating system should shut down operations, prepare for a wakeup condition (external interrupt, system timer wakeup, etc), then put the system to sleep.

Be aware that if main power is cut suddenly, the system may not have time to enter Sleep mode before onboard power fails completely. Where possible, slow the decay of external power to provide enough time to go to sleep. If your application requires "pulled plug" protection, consult ADS for further design ideas.

<sup>3</sup> Units were fully-populated evaluation systems (32MB DRAM, 16MB flash, SA-1110/1111, Ethernet, CAN, Serial, V<sub>EE</sub>, ADSmartIO, etc).

<sup>4</sup> Sleep mode test conditions: 1. Set Vperm=5V, 2. put system to sleep, 3. disconnect all other external power, 4. measure current (Iperm).

## 4.7 EMI/RFI and ESD

The Graphics Master incorporates a number of industry-leading features that protect it from electrostatic discharge (ESD) and suppress electromagnetic and radio-frequency interference (EMI/RFI). Transient voltage suppressors, EMI fences, filters on I/O lines and termination of high-frequency signals are included standard on all systems.

Many products using ADS single-board computers have successfully completed FCC emissions testing as a part of their design cycle. Because ADS supplies only the single-board computer and not fully integrated systems, ADS cannot provide meaningful system-level emissions test results.

## 4.8 Electrical Specifications for I/O Ports

### 4.8.1 ADSmartIO™ Controller

*As Digital Outputs:*

Push-pull 3.3V CMOS  
Sink up to 20 mA

*As Digital Inputs:*

CMOS,  $V_{DD}=3.3V$  (3.8V max)  
Logical low @  $<0.3 V_{DD}$ , logical high @  $> 0.6V_{DD}$   
Software-selectable MOS pull-ups, 35-120k $\Omega$

*As Analog Inputs (Port A/Columns):*

10-bit, 0~2.4V  
Input impedance: 100M $\Omega$ , with overvoltage protection  
 $V_{max}=V_{DD}=3.3V$

*Additional information:*

Row and column I/Os have 1k $\Omega$  series resistance and overvoltage protection to ground. SMTIO0-5 I/Os are directly connected to I/O controller without external protection. Control pullup resistors by writing to bits of IO port when the port is configured as a digital input (bit mask 1=enable, 0=disable).

### 4.8.2 UCB 1200

*As Digital Outputs:*

Push-pull 3.3V CMOS  
Maximum output current: 4 mA

*As Digital Inputs:*

CMOS,  $V_{DDD}=3.3V$  (3.8V max)  
Logical low @  $<0.3 V_{DDD}$ , logical high @  $> 0.7V_{DDD}$

*Analog Inputs:*

10-bit, 0~9.9V (11.0V max)  
Input impedance: 1.3k $\Omega$  (0.76 voltage divider)  
Range of maximum reading (0x3ff): 9.2-10.5V.

*Additional information:*

Digital I/Os have 1k $\Omega$  series resistance with overvoltage protection.

### 4.8.3 SA-1110

*As Digital Outputs:*

Push-pull 3.3V CMOS  
Maximum output current: 2 mA

*As Digital Inputs:*

CMOS,  $V_{DD}=3.3V$  (3.6V max)  
Logical low @  $<0.2 V_{DD}$ , logical high @  $> 0.8V_{DD}$

*Additional information:*

Digital I/Os GPIO24-27 have 1k $\Omega$  series resistance  
GPIO24 also has 10k $\Omega$  pull-down and controls the buffered PNL\_ENA signal (3.7.14).

### 4.8.4 LCD Panel

LCD display panels have a wide range of voltage and data requirements. The Graphics Master has a number of adjustable voltages to support these requirements.

*PNL\_PWR:*

Voltage is 3.3 or 5V, depending on setting of JP1.  
Must be set to match panel specifications.

*Vee:*

Bias voltage used for many passive panels.  
Can be positive, negative or fixed at "12V" (from J5). Selected with J19.  
Adjustable with VR1; typically in the range of 20 to 30V.  
Voltage and current range can be changed at the factory for specific panels or needs.

*VCON:*

Voltage used by some panels to adjust contrast.  
Adjustable between 0V and PNL\_PWR with 10k $\Omega$  potentiometer VR2.  
VCON is populated as needed, and may not be available on some evaluation systems.  
In production, VCON can be set to a specific value with fixed resistors.

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## 5 Board Revision History

### 5.1.1 Identifying the board revision

The product revision number of the Graphics Master is etched on the underside of the printed circuit board. That number is 170110-9000x, where "x" is the board revision.

### 5.1.2 Revision History

The following are the most significant changes that have occurred.

#### *Rev. A:*

- (See section 1.2 for differences from Graphics Client Plus)

#### *Rev. B:*

- Corrections support low-power sleep mode

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